



ARL

Taming the Torrent: Future Military Signal Processing and Information Fusion

Dr. Philip Perconti
Director (A)

Dr. Christopher Morris
Director's Technical Assistant

September 23, 2016



Vision

The Nation's Premier Laboratory for Land Forces.

Mission

DISCOVER, **INNOVATE**, and **TRANSITION**
Science and Technology to ensure dominant
strategic land power

Making today's Army and the next Army obsolete



U.S. ARMY
RDECOM

UNCLASSIFIED

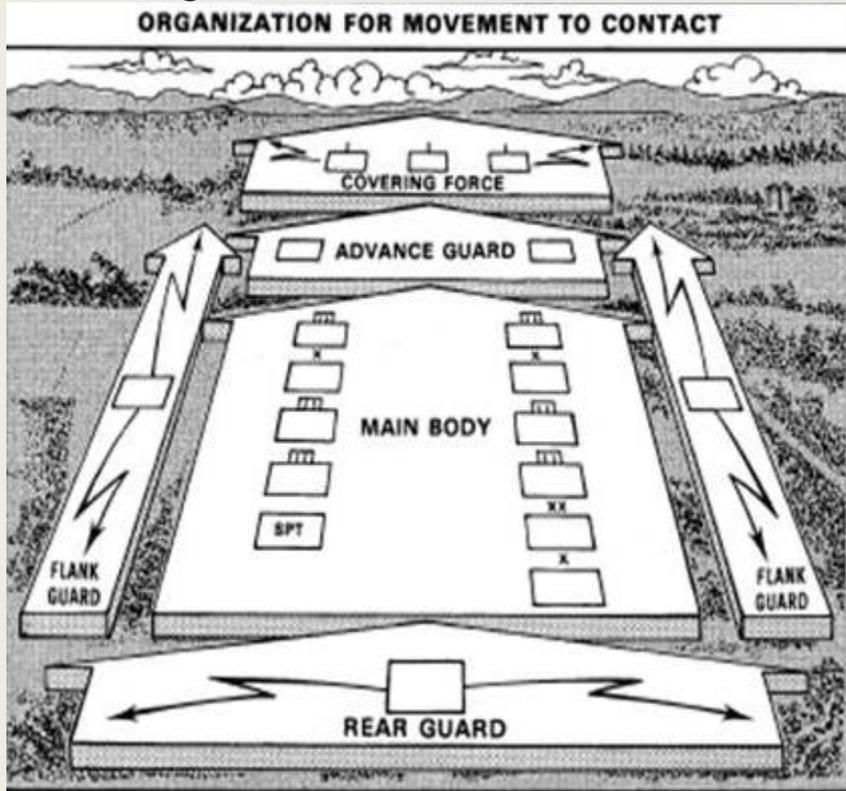
TRADOC Unifying Concept for the Future



ARL

AirLand Battle:

Flight outnumbered, and win



Unified Land Operations:

Prevail in a complex world



ARL's S&T Strategy- Perform fundamental research to inform the *Army Operating Concept* for the "Deep Future" (2050)



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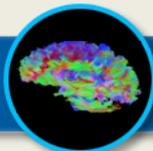
ARL S&T Campaigns

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Functional Campaigns

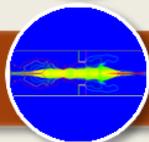
Cross Cutting Campaigns

SOLDIER



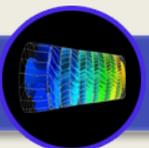
Human Sciences

SHOOT



Sciences for Lethality & Protection

MOVE

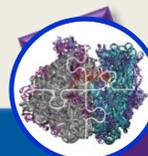


Sciences for Maneuver

COMMUNICATE



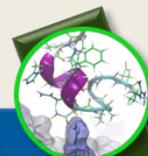
Information Sciences



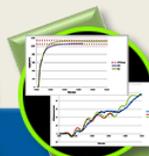
Extramural Basic Research



Computational Sciences



Materials Research



Assessment and Analysis

- **A coherent understandable strategy**
- **Ultimately leading to new warfighter capabilities**

ARL Campaign Publications <http://www.arl.army.mil/publications>



Human Agent Teaming

Artificial Intelligence and Machine Learning

Cyber and Electromagnetic Technologies for Complex Environments

Distributed and Cooperative Engagement in Contested Environments

Tactical Unit Energy Independence

Manipulating Physics of Failure for Robust Performance of Materials

Science of Manufacturing at the Point of Need

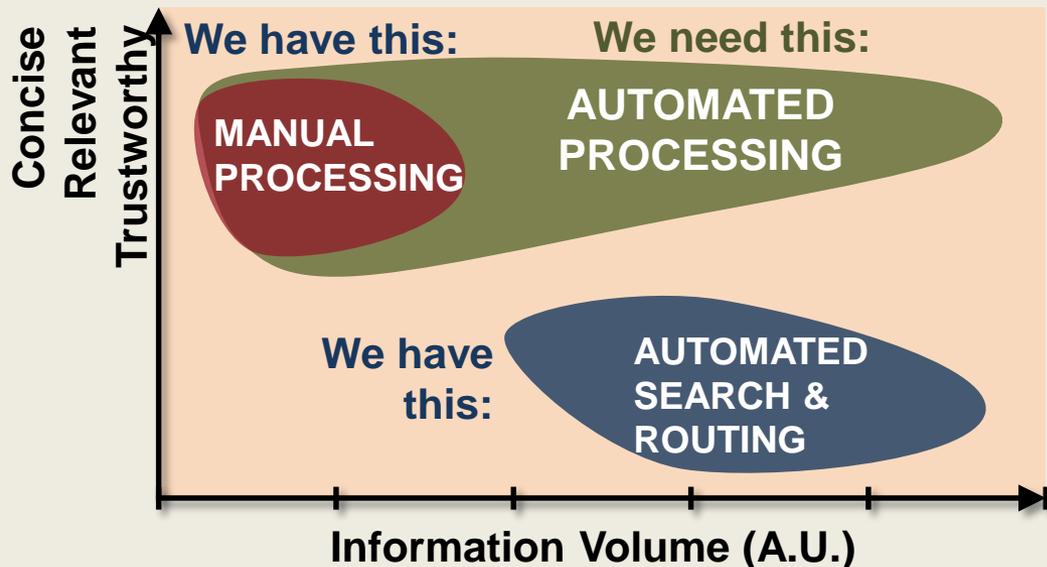
Accelerated Learning for a Ready and Responsive Force

Discovery



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Data Processing Challenges **ARL**



Commercial Efforts

- Industry investing heavily in deep learning (~\$1B in start-ups since 2010 with 300 this year alone, >\$1B OpenAI, Google \$400M DeepMind acquisition, Google release of Tensor Flow, etc.)

Army-Specific Challenges

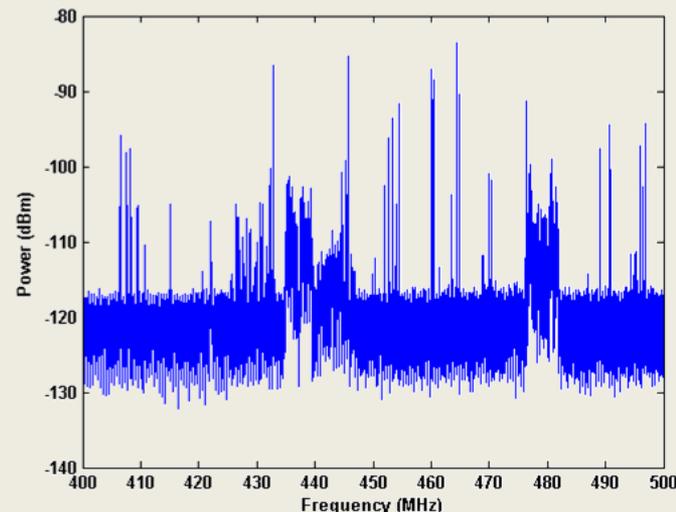
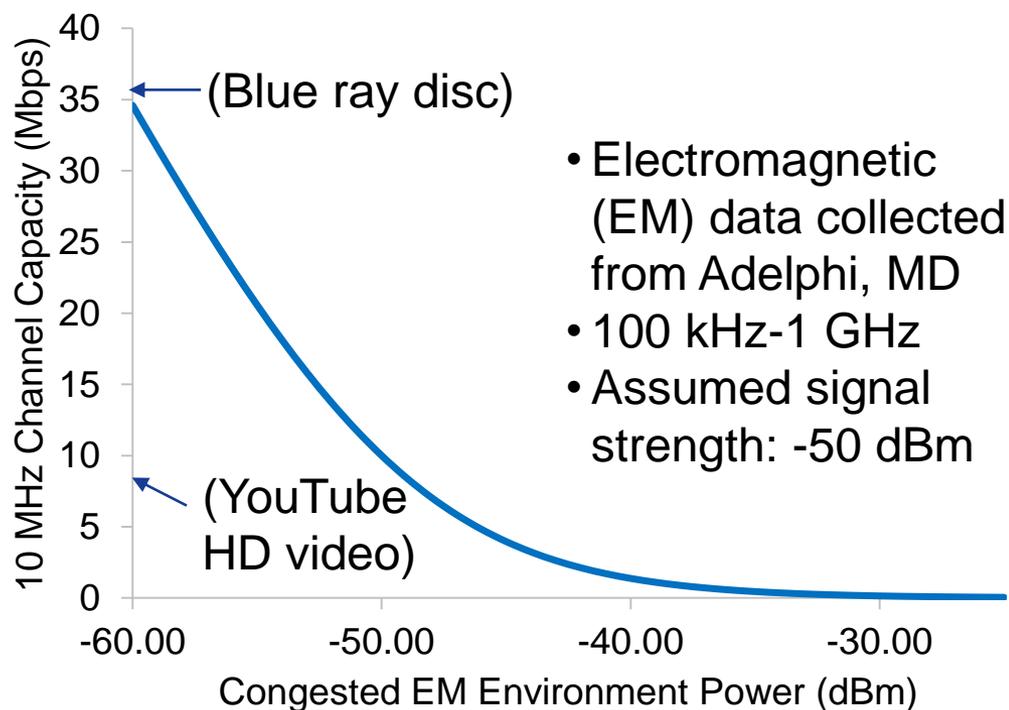
- Constrained and contested environments
- Limited training datasets
- Heterogeneous computational and communication
 - Limited power/energy resources
 - Ensure trust/credibility





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Electromagnetic Congestion



Typical 100 kHz sample



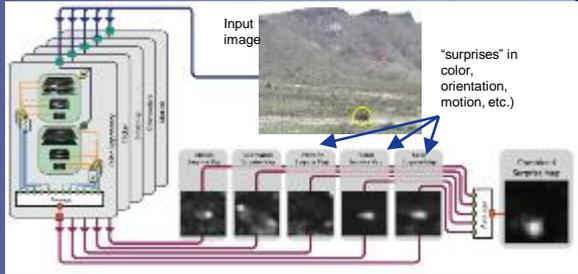
U.S. FCC raised >\$41 billion by auctioning EM space to the private sector

- Maximum channel capacity = **situational awareness** in current mode of operation
- Background EM congestion high and continues to increase
- Problem is exponentially more significant in a hostile environment



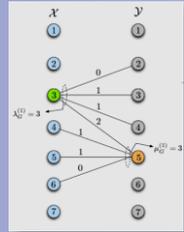
Deep Learning

- Human trainers
 - Machine learning from sparse training sets



Information Fusion

- New algorithms for increased confidence from hard / soft information sources



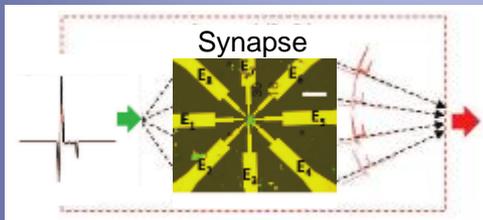
Human/Autonomy Teaming

- Humans adapt
 - Robotics augment human cognition
 - Teams outperform individuals



Neuromorphic Processing

- Pre-processing (i.e., DVS cam.)
 - Emulate bio-Materials, 1000X lower power



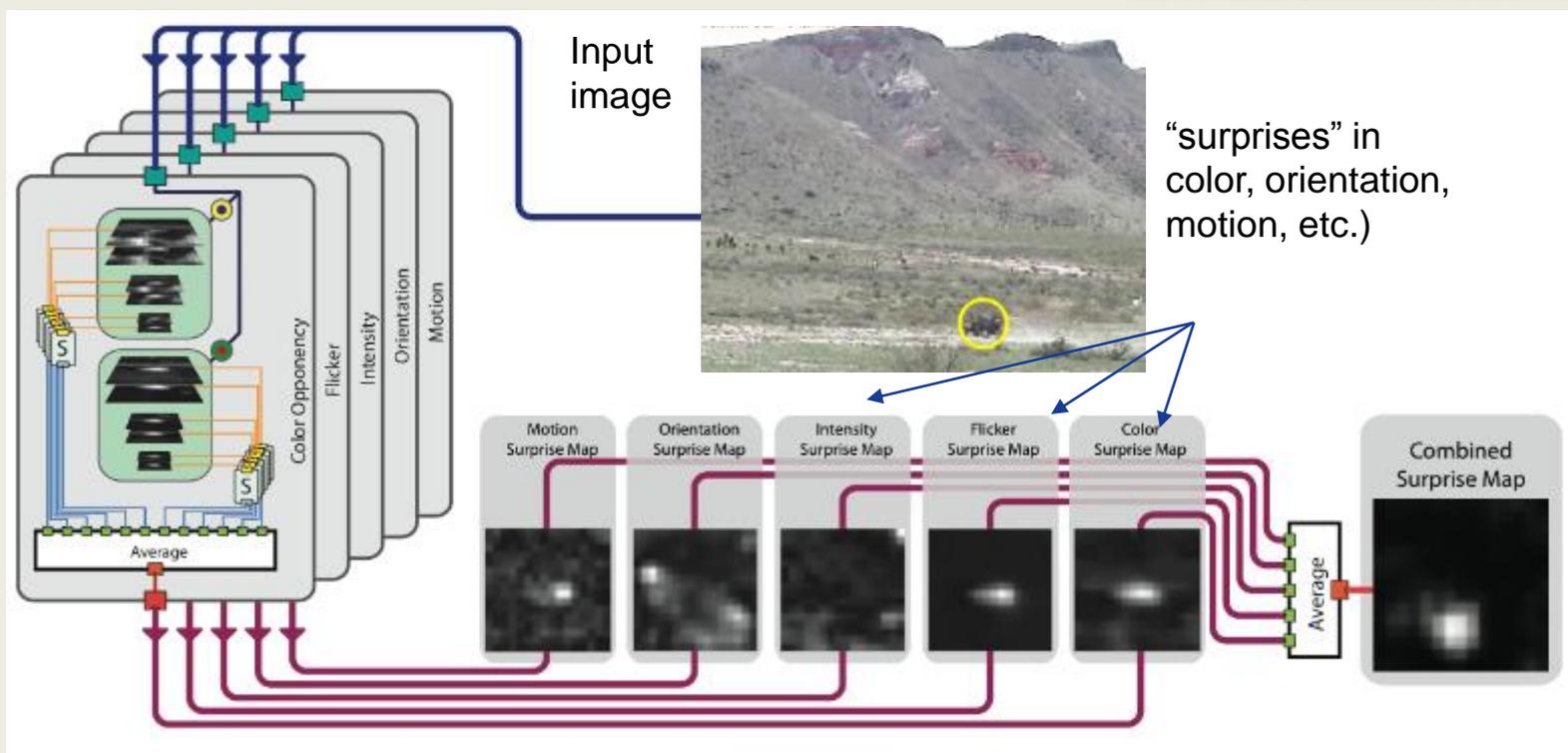
Taming the Torrent: Assuring timely and essential information for contested physical, cyber, and social battlefields





Army Deep Learning

- Military-specific training datasets are sparse
(e.g., most ISR imagery is normal activity)
- Need to implement efficient processing at the sensor
- One approach: “Surprise” detection



**Human-Autonomy Interaction Today:**

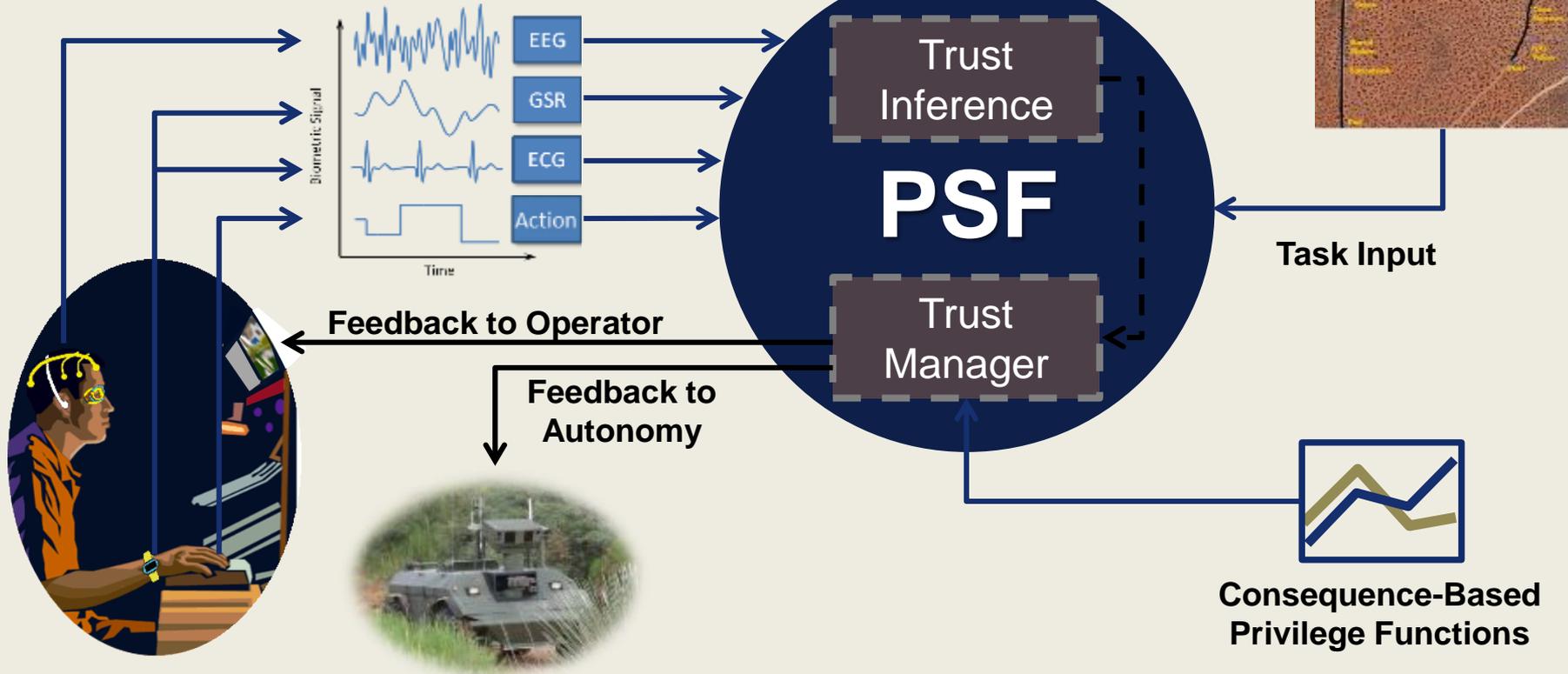
- Humans adapt to complexities of real-world operational environments
- Consequently, humans **allowed** or even **required** to make critical decisions

**Future:**

- Dynamic reinforcement learning, guided through feedback provided by human oracles
- Robotic assets augment human cognitive limitations
- Demonstration of Heterogeneous (human-bot) teams outperforming homogeneous teams (human-only / bot-only)



How do we share authority and account for dynamic performance fluctuations of humans in methodologies designed to integrate unique capabilities of human-autonomy teaming?

**PSF: Privileged Sensing Framework****Operator State and Performance Sensors**

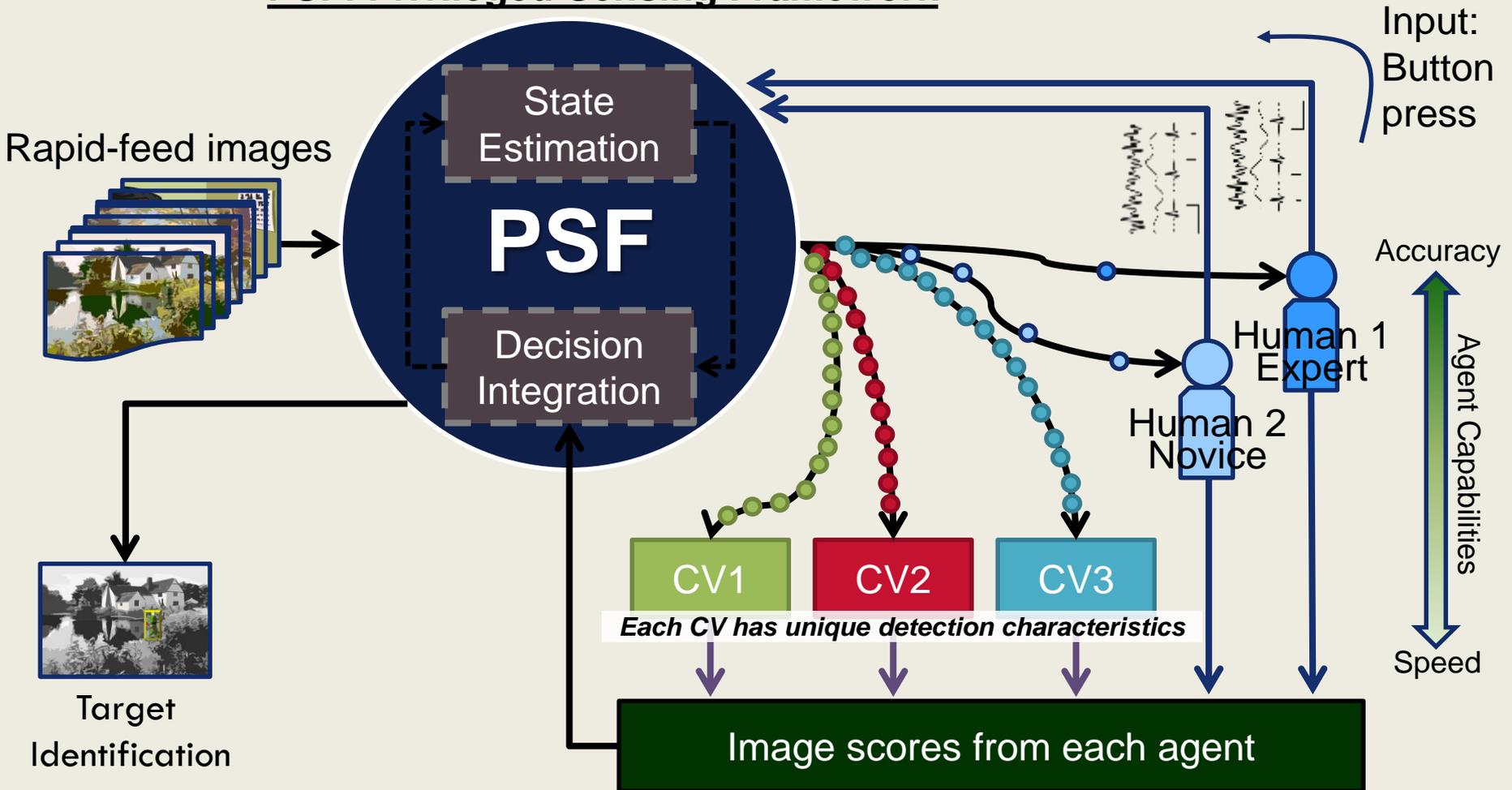
Develop and validate management of autonomy trust by incorporating *a priori* knowledge of perceived risk and consequence in order to appropriately balance operator and autonomy capabilities



Target Recognition



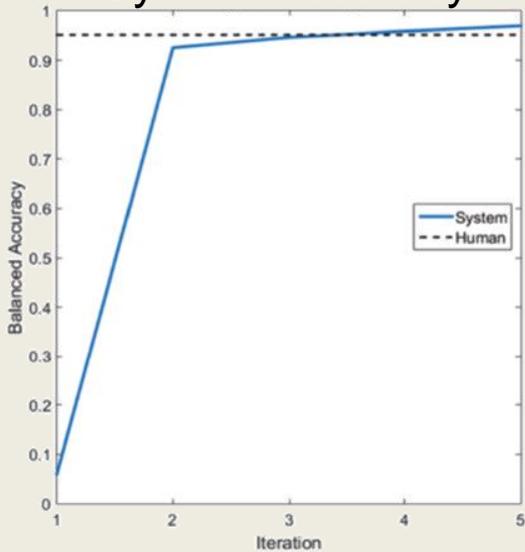
PSF: Privileged Sensing Framework



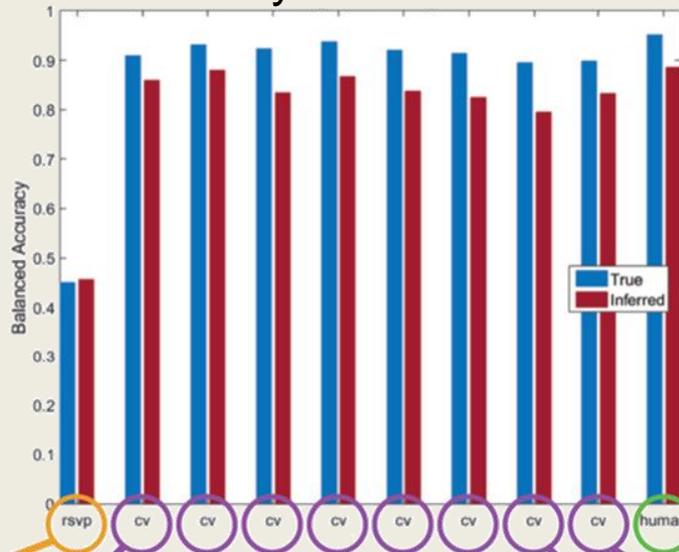
Improved joint human-autonomy target recognition by leveraging and combining unique strengths of each agent



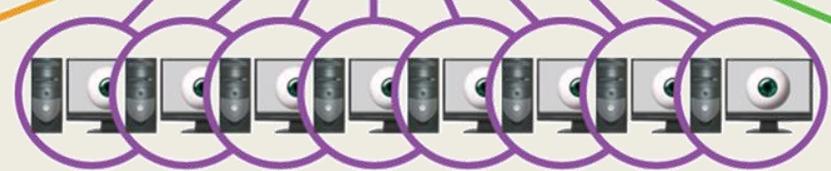
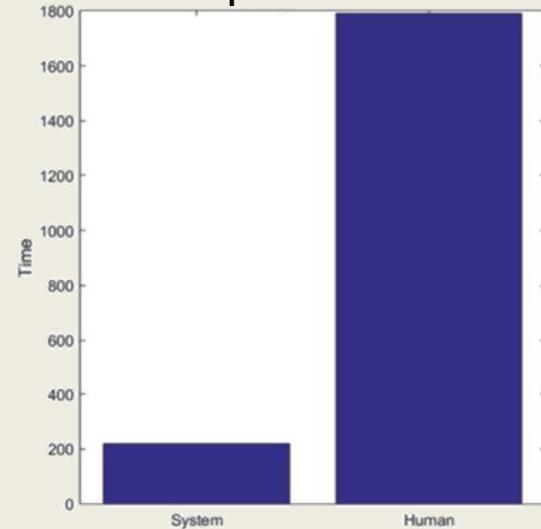
System Accuracy



Accuracy For 5th Iteration



Completion Time

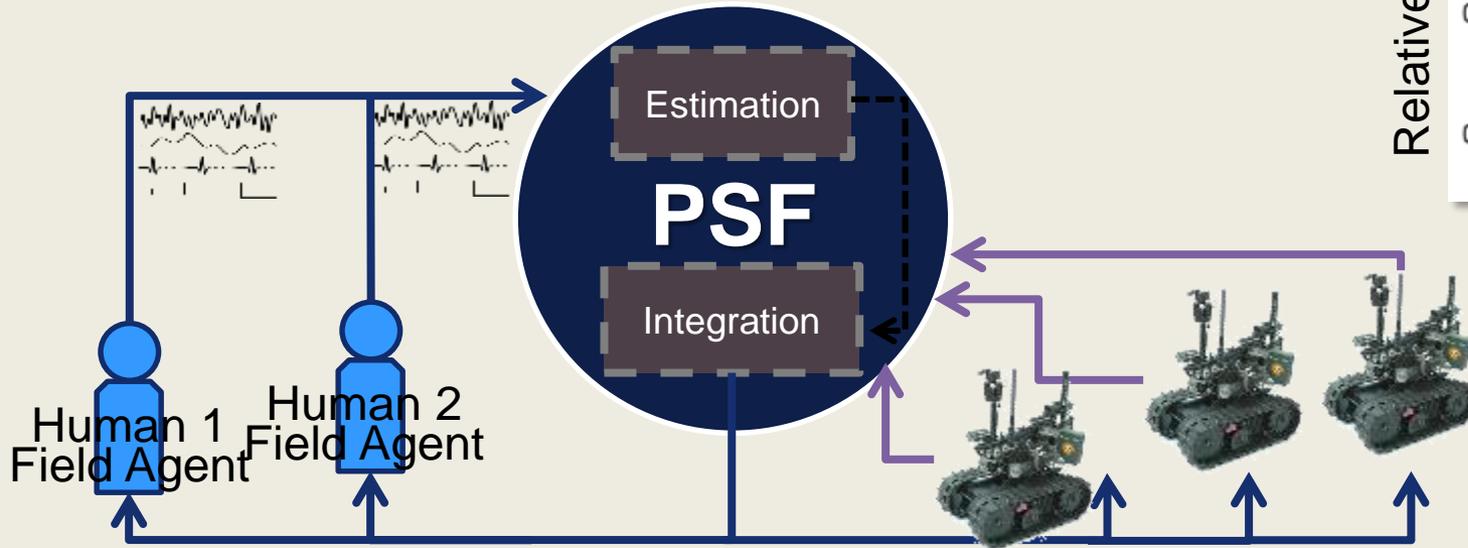
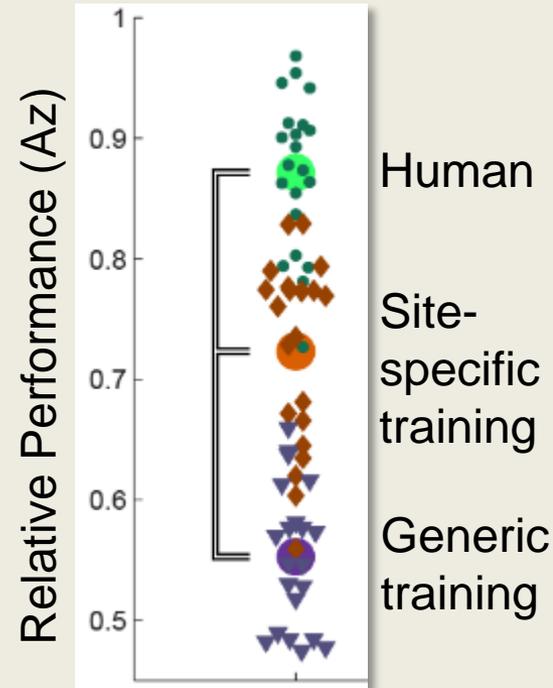
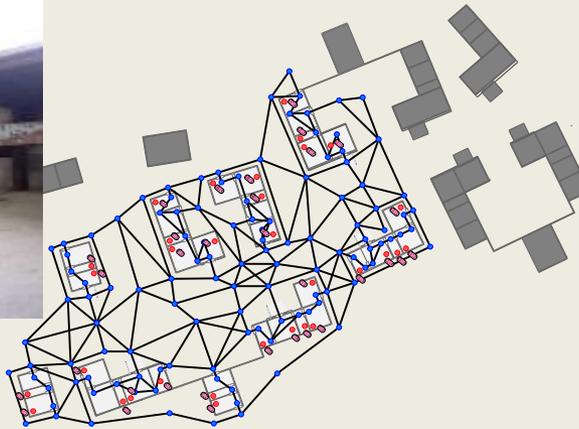



 +
  x8
 +
 
 = Accuracy: 0.969 Time: 218s


 = Accuracy: 0.952 Time: 1791s



Robotic Exploration



Improved joint human-aided autonomous navigation loop closure

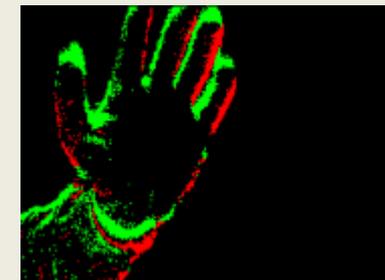


Desired Outcomes

- Push processing forward to the sensor (EO/IR, hyperspectral, RF, acoustic, CBRNE) to pre-process, send only relevant info.
- Lower susceptibility to Electronic Warfare (jamming, hacking)
- Utilize power efficiently for persistent operation

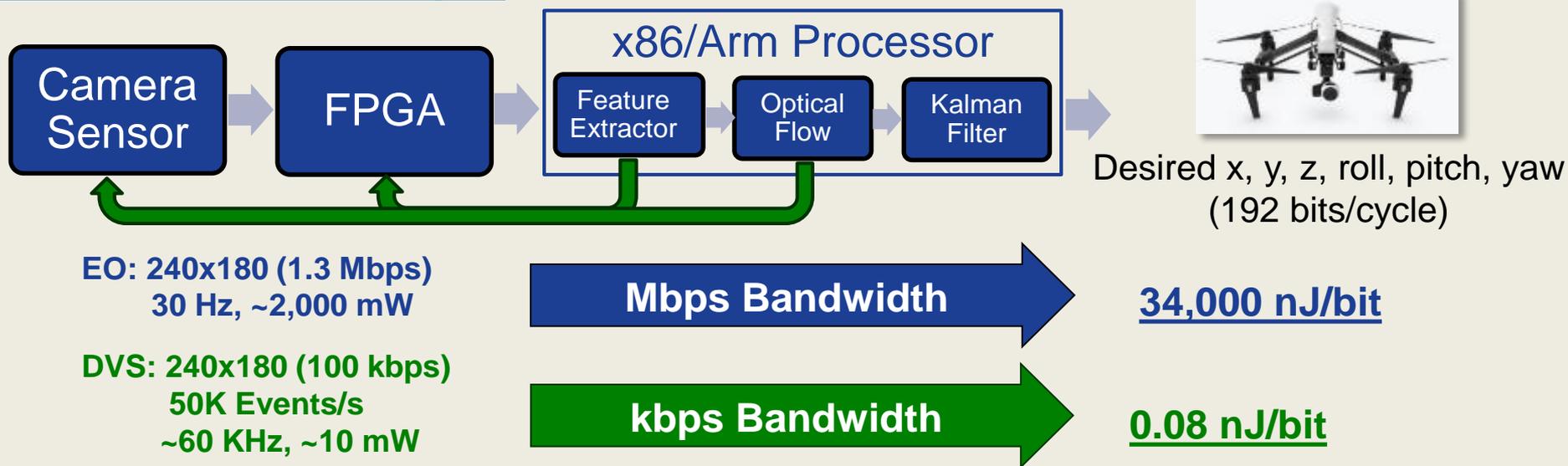


Traditional Electro-Optic (EO) imaging

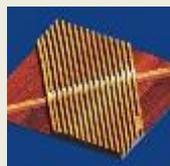
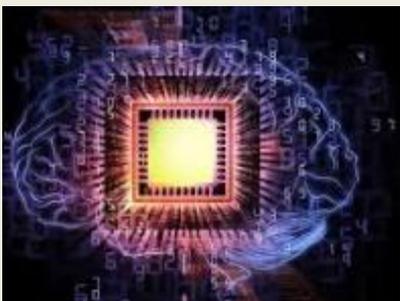


Dynamic Vision Sensor (DVS)

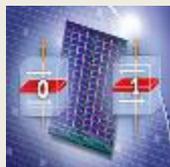
Current Research Example:



Future Research: Can both EO and DVS functions be carried out on one sensor?



Memristor



Spin Torque

Brain-Inspired Processing

- Exceptionally low power (1000x)
- Massively parallel
- Distributed & redundant coupled storage and computation
- Simple unified building blocks (neuron-like)
- Should be compatible with commercial Si processing

Limitations & Applications

- Only implements neural networks
- Ideally suited for: Image Discrimination, Pattern Matching, Machine Learning for Big Data, Decision-Making (Autonomous Vehicle Control, Tactical Planning), and **Dynamic Vision Sensors (DVSs)**



DVS For Image Classification

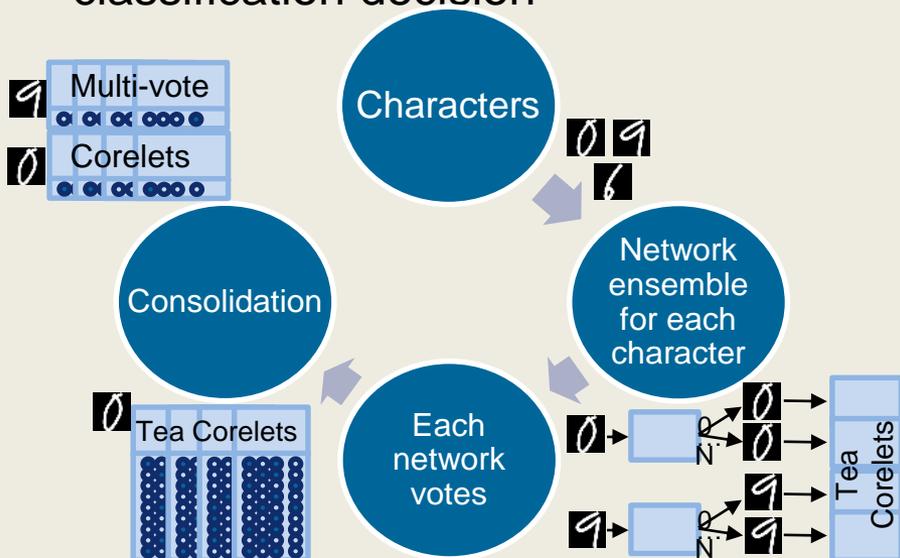
Challenge: Spikes generated from a moving stimulus typically not present simultaneously

Solution: Layer of short-term memory neurons on top of the classifier to increase probability of joint spikes

Object classification through motion patterns

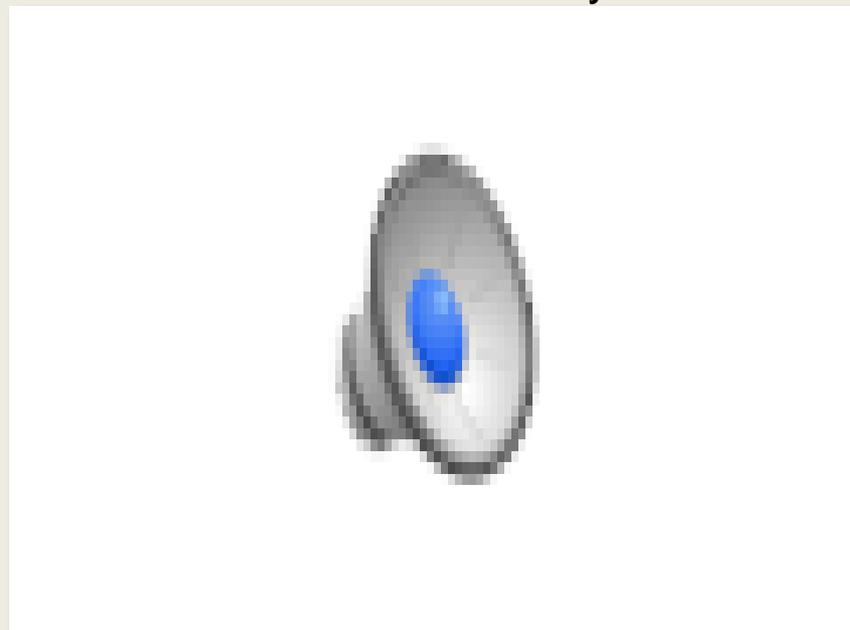


- DVS camera mounted on a pan-tilt table to create additional spikes
- 1000 samples from the N-MNIST dataset (spiking version of MNIST—28x28 pixel handwritten samples)
- 100 ms sampling intervals
- 5 core probabilistic network trained and implemented on TrueNorth (IBM)
- Weighted max vote for sample classification decision



DVS output

Memory accumulation



(1,2,3,... playback at 1/10th real time)

- Memory filter improved classification accuracy from 30% to 81%
- Streaming video benefits enabled at the tactical edge (power, bandwidth consumption each 200X lower)

**Problem:**

- Some information sources may be unreliable, biased, or conflicting

Solution:

- Generative models using estimation-maximization to estimate accuracy
- Cramer-Rao Lower Bounds shown to characterize uncertainty of estimates
- Implicit assumption is that on average, a majority of sources tell the truth



Boston Bombing

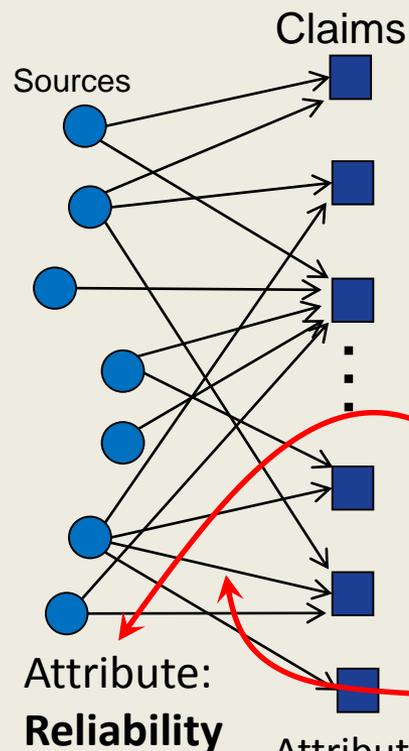


Hurricane Sandy



Egypt unrest

Sample (anonymous)
tweet datasets



- Define a_i as:

- $P(\text{source}_i \text{ makes a correct claim} | \text{the claim})$

- Define b_i as:

- $P(\text{source}_i \text{ makes an incorrect claim} | \text{the claim})$

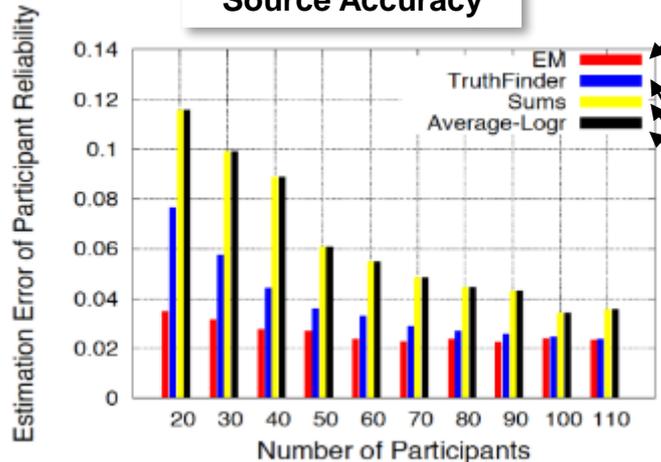
- What are the source reliability parameters that maximize the probability of received observations?

$$P(SC|\theta) = \sum_z P(SC, z|\theta)$$

Insight: Source generative models provide a means to develop constraint-aware fact-finders and performance bounds

Synthetic Data:

Source Accuracy

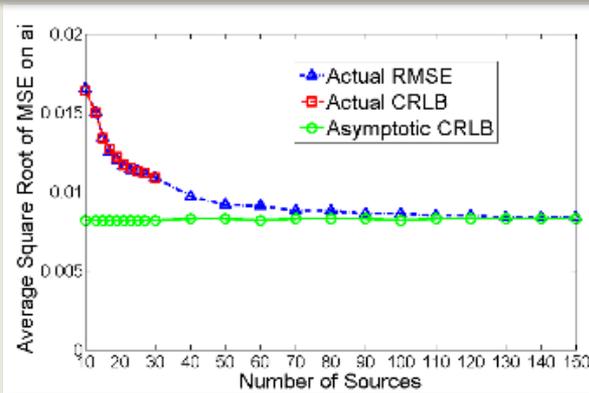


Estimation-maximization (EM)

Baseline "fact-finding" approaches

Similar improvements obtained using EM for reducing false negatives & positives (claim accuracy)

EM estimator achieves Cramer-Rao Lower Bound (CRLB)



(Wang, Abdelzaher, Kaplan, Social Sensing: *Building Reliable Systems on Unreliable Data*, Morgan Kaufmann, March 2015)

Real Data:

Accuracy of Finding Free Parking Lots on UI Campus



Experiment:

- 106 parking lots
- 46 actually free
- 30 participants reported via cell phone app
- 901 marks collected

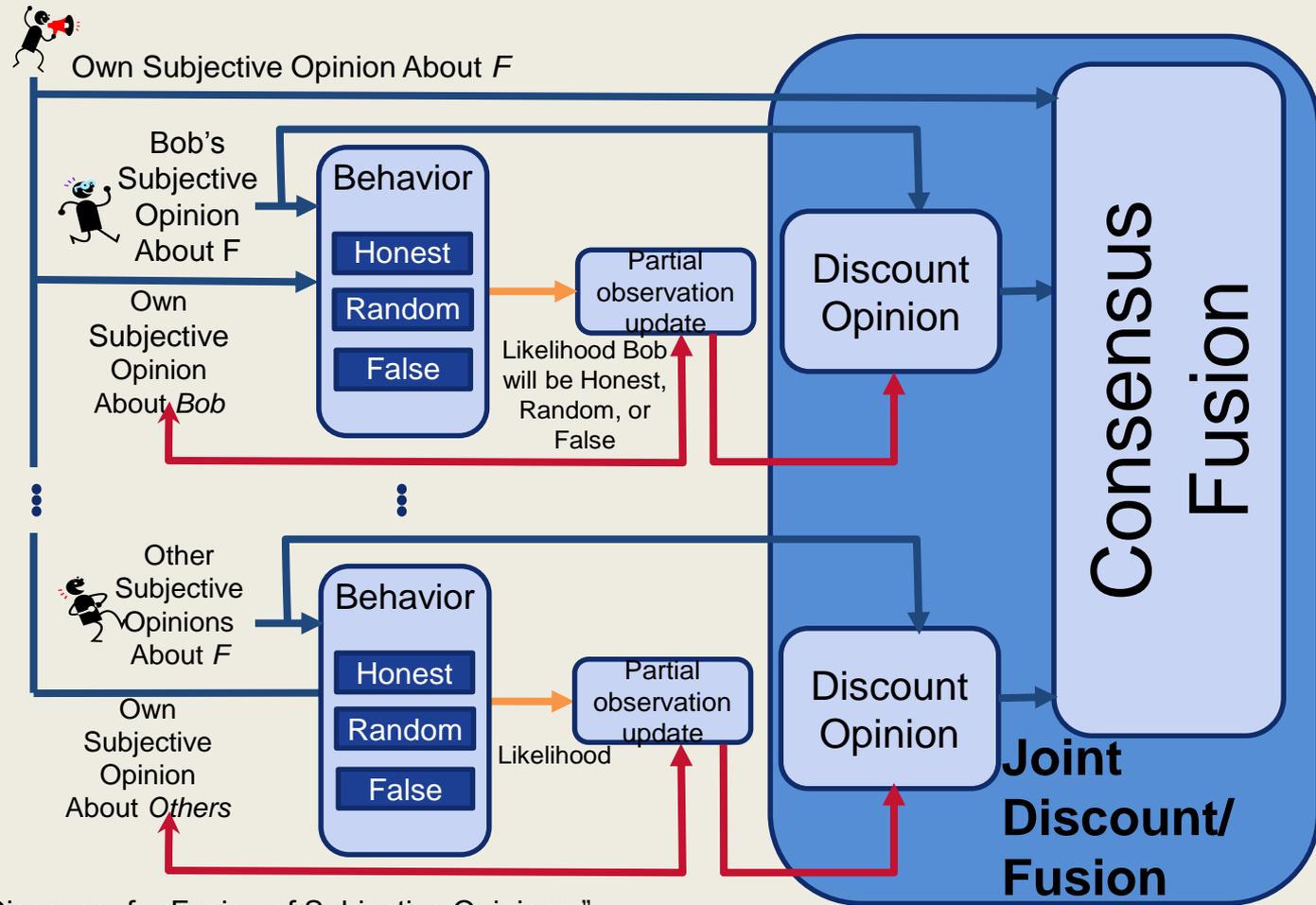
Y: Free Parking lot : no charge after 5pm
N: Not free parking lot

Schemes	False Positives	False Negatives
EM	6.67%	10.87%
Average-Log	16.67%	19.57%
Truth-Finder	18.33%	15.22%
Voting	21.67%	23.91%

Current work: Experiments on Twitter tweet credibility using Apollo platform



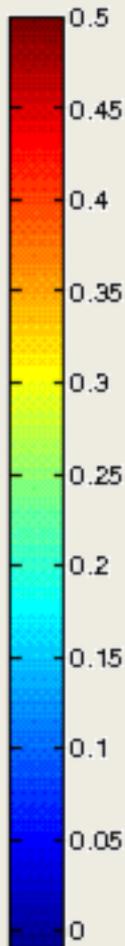
- Sources may report conflicting information (incompetence, malicious deception, faulty electronics, etc.)
- Typically, source reports are discounted before fusion.
- Here, a new joint discount/fusion method improves performance by finding coherence in source reports, and even increases confidence when sources are (consistently) false.



“Source Behavior Discovery for Fusion of Subjective Opinions,”
ISIF/IEEE Fusion 2016, Heidelberg, Germany, 2016)

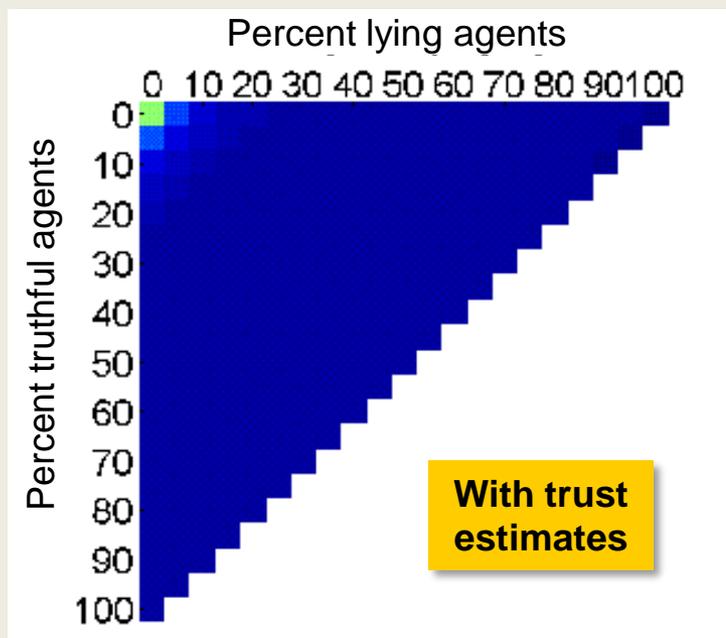


RMS
fusion
error:

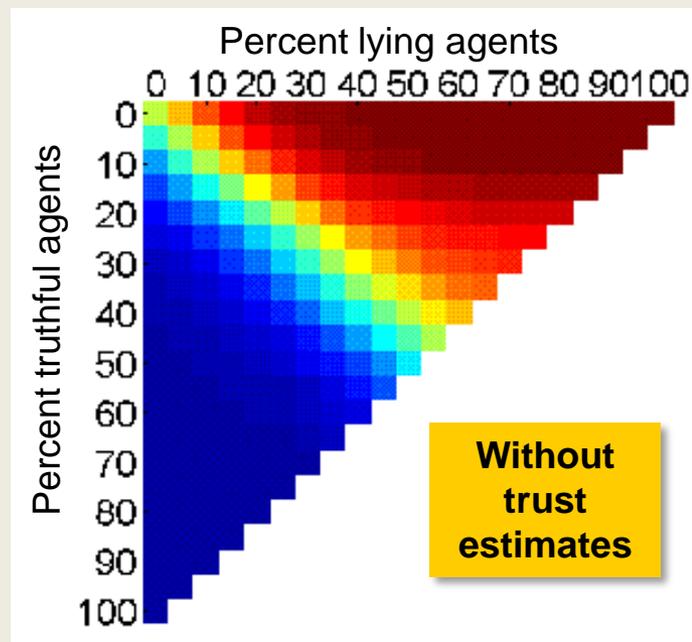


Experiments over simulated data (100 agents):

- Truthful agents defined as 70% true, 15% false and 15% random
- Lying agents defined as 70% false, 15% true, and 15% random
- Any remaining agents (100-X-Y) are random agents, defined as 70% random, 15% true, 15% false



Method works well even for false agents, as long as random agents are <90%



When sources are unknown, methods lock onto coherence and report truth as long as truth > false.



Open Campus Initiative



Past: Current Defense Laboratory Model

Gates and high walls provide 20th century security, but are barriers to 21st century innovation



Defense laboratories relatively unchanged since inception (NRL 1923)

Present & Future: Open Campus Initiative

Reduction in barriers to facilitate collaboration with academia, industry, and small business



Less bureaucracy and paperwork



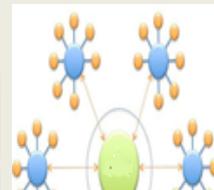
Open areas for researchers and access to existing facilities



Collaboration between ARL and external scientists



Career path for students and scientists



Hub and Spoke Model



Collaborator presence through EUL



Novel staff opportunities

An enhanced defense research environment that fosters discovery and innovation through collaboration on fundamental research



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Sensor Information Testbed Collaborative Research Environment (SITCORE)



Potential end-users for technology transition



Military SMEs



ARL S&Es



CTA & ITA Partners



Description:

Virtual research environment allowing collaboration from other locations including DoD, industry, academic, & coalition facilities



Coalition Partners



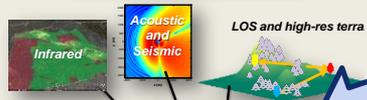
Collaborative R&D Sandbox

How to Access:

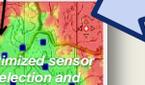
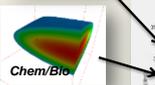
<http://aodr.arl.army.mil>



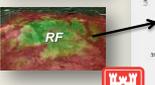
Gaian Database



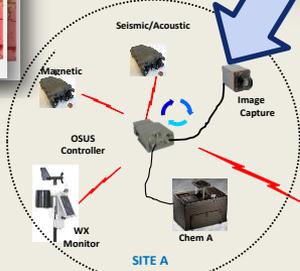
LOS and high-res terra



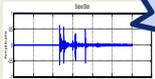
1. Optimized sensor selection and placement



Software Algorithms & Tools



ISR Sensor Assets



Multimodal Datasets



Network Science Research Laboratory (NSRL)

Algorithms developed under other government programs, e.g.:

- Improved Fusion Algorithm System (IFAS), developed under Army SBIR

Military-relevant datasets via the Automated Online Data Repository (AODR), e.g.:

- "Bluegrass" (Wide Area Motion Imagery, U.S. restricted)
- "Belgium" (unrestricted)



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Questions?