

Quantized Fusion Rules for Energy-Based Distributed Detection in Wireless Sensor Networks

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1 Introduction

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- 2 Problem Formulation

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Motivation

- Distributed detection has been attracting significant interest in the context of WSNs [Chamberland 2007] and [Barbarossa 2013].

Challenges

Objective

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- To improve the detection by fusing the measurements provided by various SNs in a manner that:
 - 1 Efficiently utilizes the scarce bandwidth.
 - 2 **Overcomes the limitations of a fading wireless channel.**

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- The channel fading effect on distributed detection was tackled by Chenn [Chenn 2006].

1. Introduction

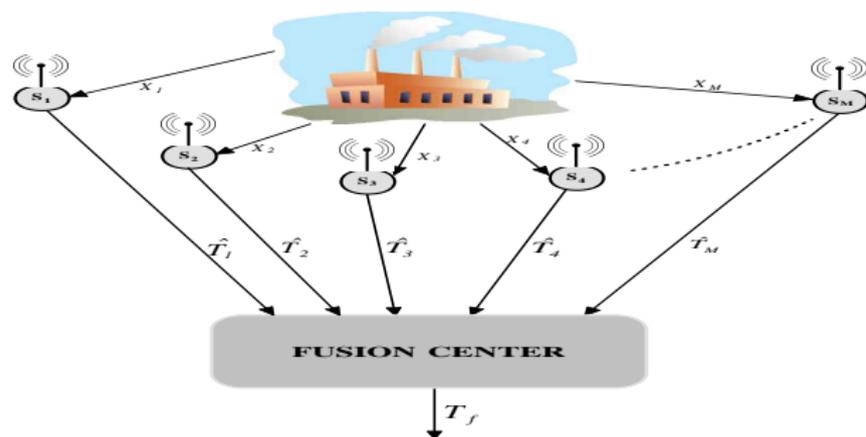
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- The channel fading effect on distributed detection was tackled by Chenn [Chenn 2006].
- Barbarossa and Sardelliti addressed both issues of limited bandwidth and channel imperfections. They optimized the transmission power for the detection of a known signal [Barbarossa 2013].

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2. Problem Formulation cont'd ...



- M sensor nodes reporting to a FC tasked with the detection of any intruders.
- The intruder leaves a signature signal unknown to the WSN but deterministic.
- The i^{th} SN collects N samples corrupted by (AWGN) zero mean and known variance σ_i^2 .

2. Problem Formulation cont'd ...

System Model

- Depending on the underlying hypothesis:

$$\mathcal{H}_0 : x_i(n) = w_i(n)$$

$$\mathcal{H}_1 : x_i(n) = s_i(n) + w_i(n)$$

2. Problem Formulation cont'd ...

Optimum detection

- The intruder's signal is unknown at the SNs, hence the i^{th} SN estimates the energy of the received signal:

$$T_i = \sum_{n=1}^N |x_i(n)|^2. \quad (1)$$

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- Available bandwidth is limited.

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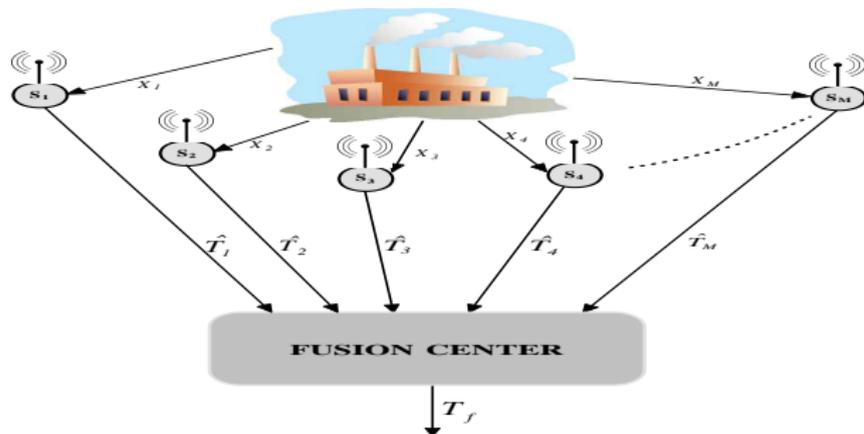
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$$T_i = \sum_{n=1}^N |x_i(n)|^2. \quad (1)$$

- SNs should send their measurements to the FC, where the ultimate detection decision will be made.
- Available bandwidth is limited.
- This approach is not always feasible in the context of WSNs .

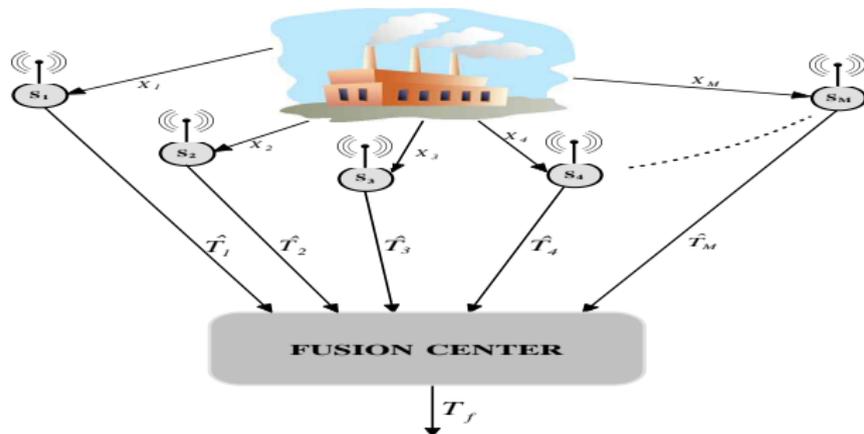
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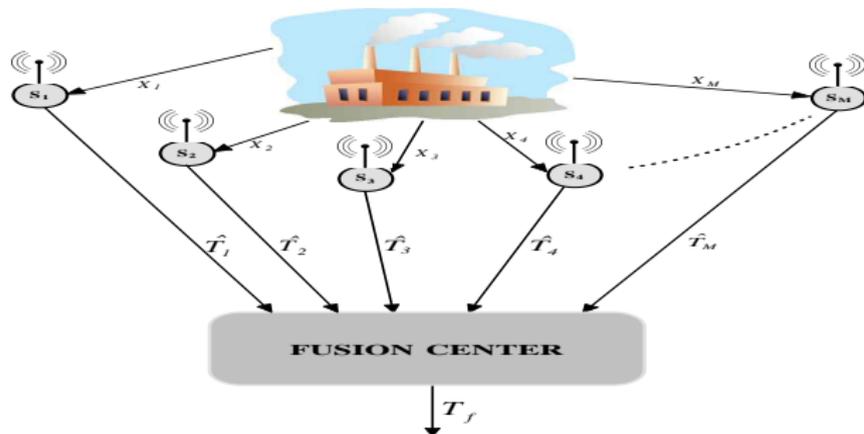
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- WSN adopts a distributed detection algorithm.
- SNs send their quantized soft decisions (i.e., the quantized local test statistics) to the FC.

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Optimum detection

- WSN adopts a distributed detection algorithm.
- SNs send their quantized soft decisions (i.e., the quantized local test statistics) to the FC.
- FC combines them to arrive at the global decision.

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Proposition

- We propose to quantize T_i with L_i bits and transmit to the FC with power p_i over a wireless channel.

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- The number of quantization bits at the i^{th} SN must satisfy the channel capacity constraint:

$$L_i \leq \frac{1}{2} \log_2 \left(1 + \frac{p_i h_i^2}{\zeta_i} \right) \text{ bits, } i = 1, 2, \dots, M.$$

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- The wireless channel conditions between the i^{th} SN and the FC:
 - 1 Suffers from zero mean AWGN with a variance of ζ_i .
 - 2 Experiences flat fading with a channel gain h_i (assumed to be iid).

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Part I

Soft Decision Fusion Rules

3. Soft Decision Fusion Rules cont'd ...

Optimal Fusion Rule cont'd ...

- Optimal soft decision fusion rule is investigated given infinite bandwidth for each WSN (no quantization is required).

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Optimal Fusion Rule cont'd ...

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- Given the local soft test statistic:

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- Given the local soft test statistic:

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- The optimal fusion rule follows from the likelihood ratio test:

$$\text{LRT}(\mathbf{T}) = \frac{p\{T_1, T_2, \dots, T_M | \mathcal{H}_1\}}{p\{T_1, T_2, \dots, T_M | \mathcal{H}_0\}} \geq \gamma \quad (3)$$

where $p\{T_1, T_2, \dots, T_M | \mathcal{H}_j\}$ is the joint probability distribution of local soft decisions under the j^{th} hypothesis.

3. Soft Decision Fusion Rules cont'd ...

Optimal Fusion Rule cont'd ...

- T_i can be adequately approximated by a Gaussian distribution with the following mean and variance:

$$E\{T_i|\mathcal{H}_0\} = N\sigma_i^2, \quad \text{Var}\{T_i|\mathcal{H}_0\} = 2N\sigma_i^4 \quad (4)$$

$$E\{T_i|\mathcal{H}_1\} = N\sigma_i^2(1 + \xi_i), \quad \text{Var}\{T_i|\mathcal{H}_1\} = 2N\sigma_i^4(1 + 2\xi_i) \quad (5)$$

where $\xi_i = \sum_{n=1}^N s_i^2(n) / N\sigma_i^2$ is the SNR at the i^{th} SN.

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where $\xi_i = \sum_{n=1}^N s_i^2(n) / N\sigma_i^2$ is the SNR at the i^{th} SN.

- Noise at different SNs assumed independent, LLR takes the form:

$$T_f = \sum_{i=1}^M \left(\frac{(T_i - N\sigma_i^2)^2}{2N\sigma_i^4} - \frac{(T_i - N\sigma_i^2(1 + \xi_i))^2}{2N\sigma_i^4(1 + 2\xi_i)} \right) \geq \gamma' \quad (6)$$

3. Soft Decision Fusion Rules cont'd ...

Optimal Fusion Rule

- The LLR can be further simplified

$$T_f = \sum_{i=1}^M a_i (T_i - b_i)^2 \quad (7)$$

$$a_i = \frac{\xi_i}{N\sigma_i^4 (1 + 2\xi_i)}, \quad b_i = \frac{N\sigma_i^2}{2}.$$

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- where $\gamma' = 2 \ln \left(\prod_{i=1}^M \gamma \left(\frac{\sqrt{2N\sigma_i^4}}{\sqrt{2N\sigma_i^4(1+2\xi_i)}} \right) \right)$.

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Suboptimal Fusion Rules

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 - 3 Optimum linear fusion

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Weighted Fusion Rule

- Replace a_i by $a_i^w = 1/2N\sigma_i^4$ and we let $b_i^w = b_i = \frac{N\sigma_i^2}{2}$. This rule approaches the optimal one when the SNR is large.

$$T_f = \sum_{i=1}^M a_i (T_i - b_i)^2 \quad (8)$$

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Equal Weight Fusion Rule

- $a_i^e = 1$ for all $i = 1, 2, \dots, M$. Also, $b_i^e = b_i$.

Optimum Linear Fusion Rule

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Optimum Linear Fusion Rule

- $T_f^l = \sum_{i=1}^M \alpha_i T_i$, where $\alpha_i = \frac{\xi_i}{N\sigma_i^2(1+2\xi_i)}$.

Part II

Quantized Soft Decision Fusion Rules

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- Now let the quantized test statistic (\hat{T}_i) at the i^{th} sensor be modeled (with L_i bits) as

$$\hat{T}_i = T_i + v_i \quad (9)$$

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- v_i is the quantization noise with uniform distribution in the interval $[-B, B]$ and variance

$$\sigma_{v_i}^2 = \frac{B^2}{3 \times 2^{2L_i}}. \quad (10)$$

Quantized Soft Decision Fusion Rules cont'd ...

Quantized Optimal Fusion Rule

- Approximating \hat{T}_i 's as Gaussian distribution, the LLR optimum fusion rule can be shown to be:

$$T_f^q = \sum_{i=1}^M a_i^q \left(\hat{T}_i - b_i^q \right)^2 \quad (11)$$

$$a_i^q = \frac{\xi_i}{N\sigma_i^4 \left(1 + 2\xi_i + \frac{\sigma_{v_i}^2}{2N\sigma_i^4} \right) \left(1 + \frac{\sigma_{v_i}^2}{2N\sigma_i^4} \right)}$$

$$b_i^q = \frac{N\sigma_i^2}{2} - \frac{\sigma_{v_i}^2}{4\sigma_i^2}$$

Quantized Soft Decision Fusion Rules cont'd ...

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- Interesting observation is that $T_f^q \rightarrow T_f$ as $N \rightarrow \infty$, regardless of $\sigma_{v_i}^2$.
- Bandwidth can be saved but at the expense of increasing both the number of collected measurements and also the detection delay.

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Quantized Soft Decision Fusion Rules cont'd...

Quantized Sub-Optimum Fusion Rules

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$$T_f^q = \sum_{i=1}^M a_i^q \left(\hat{T}_i - b_i^q \right)^2$$

- The suboptimal (quantized) fusion rules can be easily shown to be:

$$L_i \leq \frac{1}{2} \log_2 \left(1 + \frac{p_i h_i^2}{\zeta_i} \right) \text{ bits, } i = 1, 2, \dots, M.$$

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- Weighted fusion : $a_i^q = a_i^{wq} = \frac{1}{N\sigma_i^4 \left(1 + \frac{\sigma_{v_i}^2}{2N\sigma_i^4} \right)^2}$.

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 - Weighted fusion : $a_i^q = a_i^{wq} = \frac{1}{N\sigma_i^4 \left(1 + \frac{\sigma_{v_i}^2}{2N\sigma_i^4} \right)^2}$.
 - Equal fusion: $a_i^q = a^{eq} = 1$ and $b^{eq} = b^{wq} = b_i^q$.

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Quantized Soft Decision Fusion Rules

Quantized Linear Fusion Rule

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$$T_f^l = \sum_{i=1}^M \alpha_i^q \hat{T}_i$$

- The weights of suboptimal (quantized) linear fusion rules can be easily shown to be:

$$\alpha_i^q = \frac{\xi_i}{2\sigma_i^2 \left[1 + 2\xi_i + \frac{\sigma_{v_i}^2}{N\sigma_i^2} \right]}. \quad (12)$$

E. Nurellari, D. McLernon, M. Ghogho and S. Aldalameh, "Optimal quantization and power allocation for energy-based distributed sensor detection," *Proc. EUSIPCO*, Lisbon, Portugal, 1-5 Sept. 2014.

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- Using the central limit theorem, T_f^q can be approximated by a Gaussian distribution:

$$T_f^q \sim \begin{cases} \mathcal{N}(\mathbb{E}\{T_f^q|\mathcal{H}_0\}, \text{Var}\{T_f^q|\mathcal{H}_0\}) & \text{under } \mathcal{H}_0 \\ \mathcal{N}(\mathbb{E}\{T_f^q|\mathcal{H}_1\}, \text{Var}\{T_f^q|\mathcal{H}_1\}) & \text{under } \mathcal{H}_1 \end{cases} \quad (14)$$

Optimum Sensor Transmit Power Allocation

Optimization Problem

- The probability of detection implicitly depends on the transmission power through the first and second moments of test statistics.

Optimum Sensor Transmit Power Allocation

Optimization Problem

- The probability of detection implicitly depends on the transmission power through the first and second moments of test statistics.
- We can optimize the transmission powers (p_i) to maximize P_d under the constraint of a maximum aggregate transmit power budget (P_t):

$$\begin{aligned} \mathbf{p}_{opt} &= \arg \max_{\mathbf{p}} P_d(\mathbf{p}) \\ \text{subject to } \sum_{i=1}^M p_i &\leq P_t \text{ for } p_i \geq 0, i = 1, \dots, M \end{aligned} \quad (15)$$

where $\mathbf{p} = [p_1, p_2, \dots, p_M]$.

Optimum Sensor Transmit Power Allocation

Optimization Problem

- The probability of detection implicitly depends on the transmission power through the first and second moments of test statistics.
- We can optimize the transmission powers (p_i) to maximize P_d under the constraint of a maximum aggregate transmit power budget (P_t):

$$\begin{aligned} \mathbf{p}_{opt} &= \arg \max_{\mathbf{p}} P_d(\mathbf{p}) \\ \text{subject to } \sum_{i=1}^M p_i &\leq P_t \text{ for } p_i \geq 0, i = 1, \dots, M \end{aligned} \quad (15)$$

where $\mathbf{p} = [p_1, p_2, \dots, p_M]$.

- We adopt the spatial branch-and-bound strategy using the YALMIP optimization tools.

Overview

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- 3 Soft Decision Fusion Rules
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- 5 Optimum Sensor Transmit Power Allocation
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Simulations setup

- We simulate a WSN of M SNs detecting an intruder with $s_i(n) = A$, where $A = 0.1$.
- The communication noise variances set to $\zeta_i = 0.1 \forall i$ (for simplicity).
- The measurement noise variances are generated randomly and used throughout the simulations.
- The average measurement SNR for the network is defined as
$$\xi_a = 10 \log_{10} \left(\frac{1}{M} \sum_{i=1}^M \xi_i \right).$$
- In all simulations we assume perfect knowledge of ξ_i .

Simulation Results 1/6

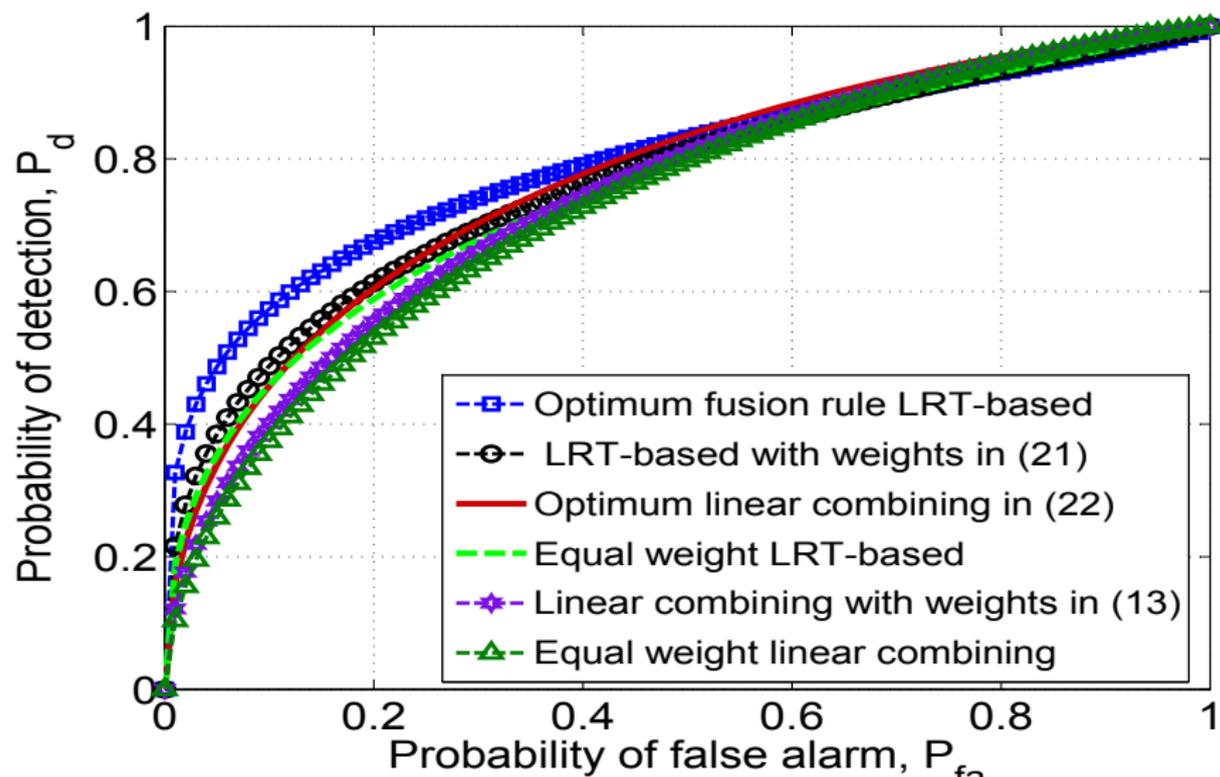


Figure: Receiver operating characteristics of six different fusion rules for $N = 10$, $M = 10$, $\xi_a = -8.5$ dB and $B = 0.5$.

Simulation Results 2/6

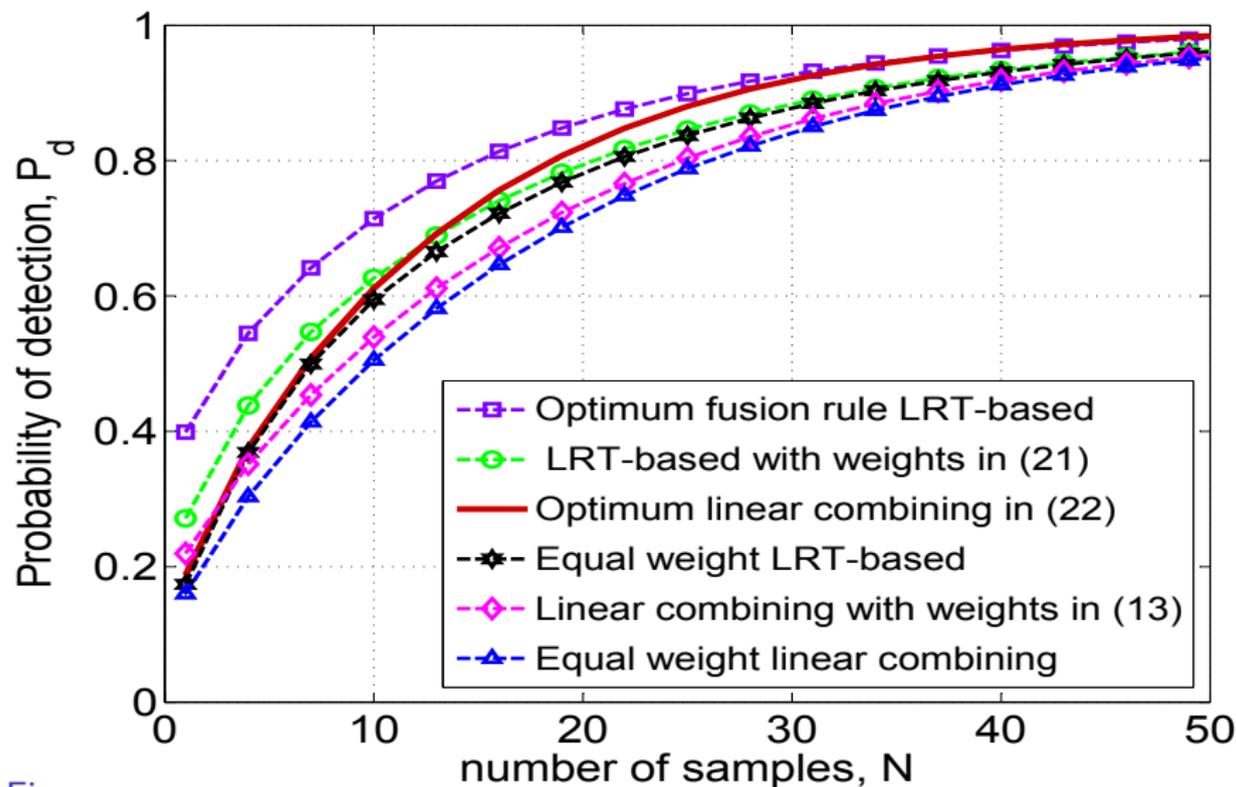


Figure: Probability of detection (P_d) versus number of samples (N) with $M = 20$, $P_{fa} = 0.1$, $B = 0.5$ and $\xi_a = 8.5$ dB.

Simulation Results 3/6

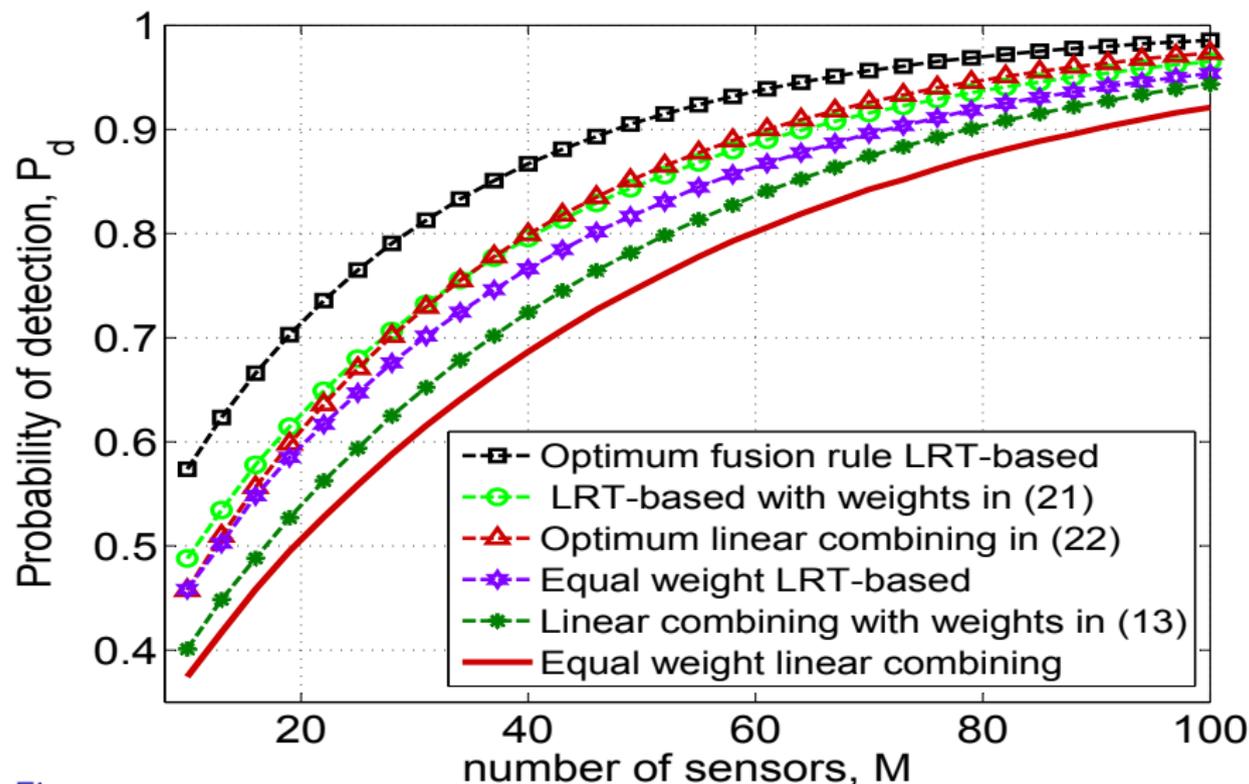


Figure: Probability of detection (P_d) versus number of sensors (M) for $N = 10$, $P_{fa} = 0.1$, $\xi_a = 8.5$ dB and $B = 0.5$.

Simulation Results 4/6

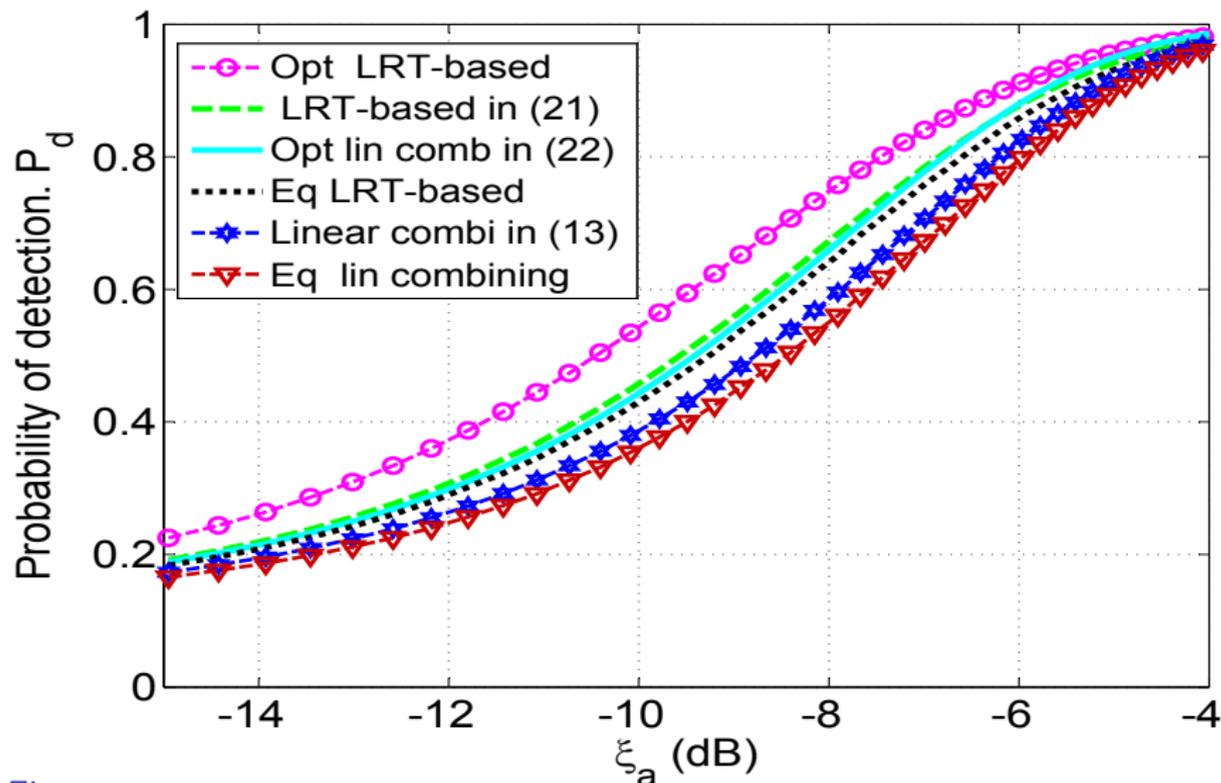


Figure: Probability of detection (P_d) versus the signal to noise ratio (ξ_a) for $M = 20$, $N = 10$, $P_{fa} = 0.1$ and $B = 0.5$.

Simulation Results 5/6

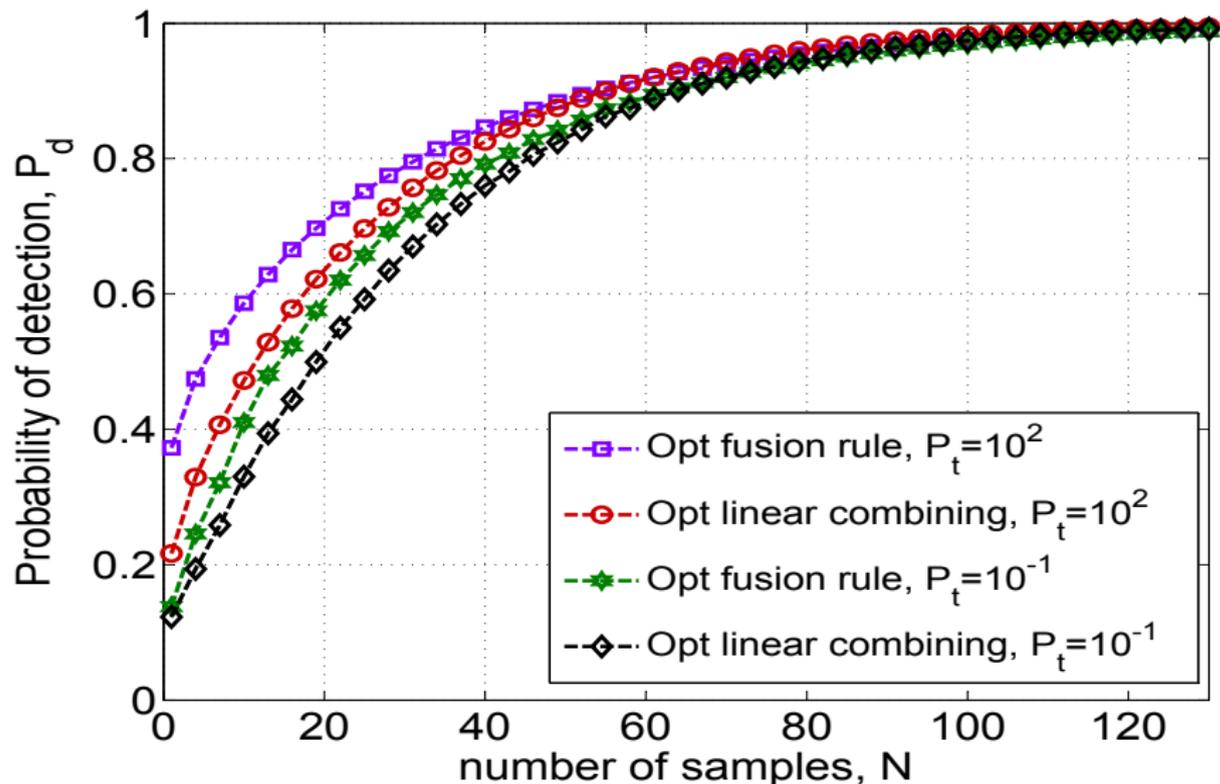


Figure: Probability of detection (P_d) versus the number of samples (N) for $M = 10$ sensors, $P_{fa} = 0.1$, $\xi_a = 8.5$ dB and $B = 1$.

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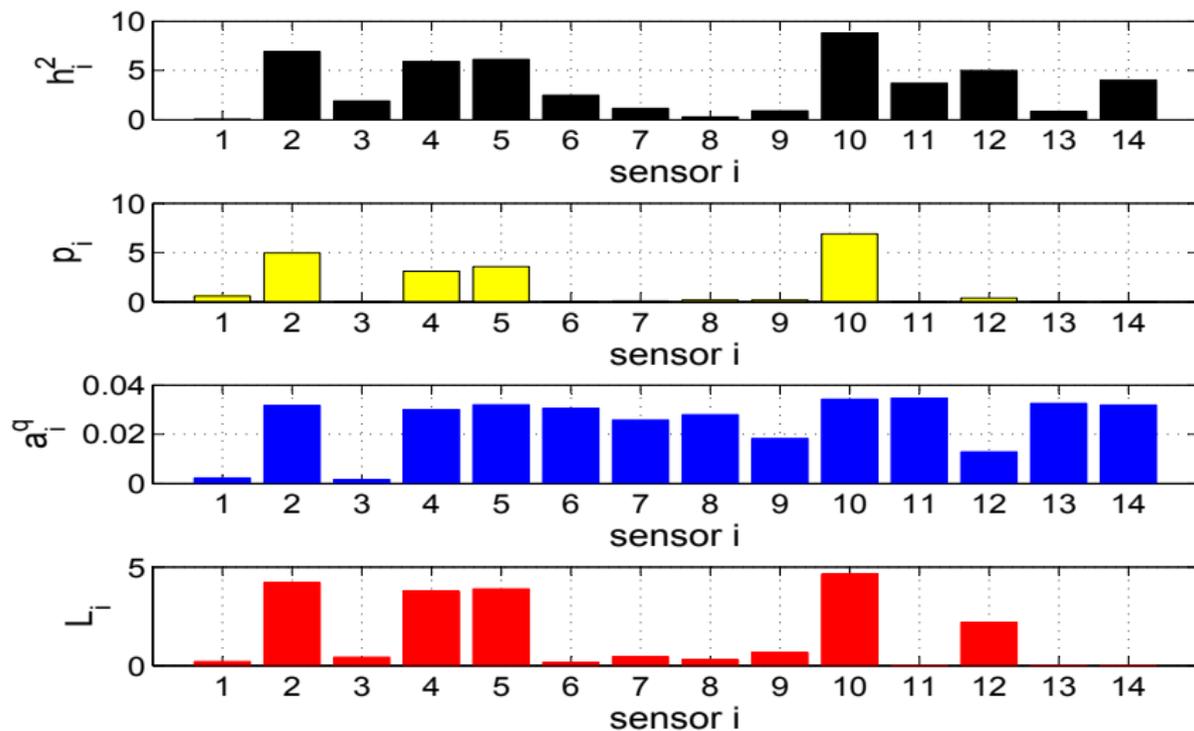


Figure: Optimum sensor transmit power and channel quantization bits allocation for $N = 10$, $P_{fa} = 0.1$, $\xi_a = 8.5$ dB and $P_t = 20$.

Conclusions

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- We show that the effect of quantization on the detection performance can be mitigated by increasing the number of measurements (N), or equivalently incurring more delay in the system.
- Finally, the SN's transmission power has been optimally allocated. Intuitively, more power is given to SNs having better channel gains and consequently increased number of bits.

Questions/Comments?